

Problems and Solutions Section 2.6 (2.59 through 2.62)

- 2.59** Calculate damping and stiffness coefficients for the accelerometer of Figure 2.23 with moving mass of 0.04 kg such that the accelerometer is able to measure vibration between 0 and 50 Hz within 5%. (*Hint:* For an accelerometer it is desirable for $Z / \omega_b^2 Y =$ constant.)

Solution: Use equation (2.90):

Given: $m = 0.04$ kg with error $< 5\%$

$$0.2f = 50 \text{ Hz} \rightarrow f = 250 \text{ Hz} \rightarrow \omega = 2\pi f = 1570.8 \text{ rad/s}$$

Thus, $k = m\omega^2 = 98,696 \text{ N/m}$

When $r = .2$, $0.95 < \frac{1}{\sqrt{(1-r^2)^2 + (2\zeta r)^2}} < 1.05 \quad (\pm 5\% \text{ error})$

This becomes $0.8317 + 0.1444\zeta^2 < 1 < 1.016 + 0.1764\zeta^2$

Therefore, $\zeta = 0.7 = \frac{c}{2\sqrt{km}}$

$$c = 2(.7)\sqrt{(98696)(.04)}$$

$$c = 87.956 \text{ Ns/m}$$

- 2.60** The damping constant for a particular accelerometer of the type illustrated in Figure 2.23 is 50 N s/m. It is desired to design the accelerometer (i.e., choose m and k) for a maximum error of 3% over the frequency range 0 to 75 Hz.

Solution: Given $0.2f = 75 \text{ Hz} \rightarrow f = 375 \text{ Hz} \rightarrow \omega_n = 2\pi f = 2356.2 \text{ rad/s}$. Using equation (2.93) when $r = 0.2$:

$$0.97 < \frac{1}{\sqrt{(1-r^2)^2 + (2\zeta r)^2}} < 1.03 \quad (\pm 3\% \text{ error})$$

This becomes $0.8671 + 0.1505\zeta^2 < 1 < 0.9777 + 0.1697\zeta^2$

Therefore, $0.3622 < \zeta < 0.9395$

Choose $\zeta = 0.7 = \frac{c}{2m\omega} = \frac{50}{2m(2356.2)}$

$$m = 0.015 \text{ kg}$$

$$k = m\omega_n^2 = 8.326 \times 10^4 \text{ N/m}$$

- 2.61** The accelerometer of Figure 2.23 has a natural frequency of 120 kHz and a damping ratio of 0.2. Calculate the error in measurement of a sinusoidal vibration at 60 kHz.

Solution:

Given: $\omega = 120$ kHz, $\zeta = .2$, $\omega_b = 60$ kHz

$$\text{So, } \frac{1}{\sqrt{(1-r^2)^2 + (2\zeta r)^2}} = \frac{1}{\sqrt{(1-.5^2)^2 + (2(.2)(.5))^2}} = 1.288 > 1$$

$$\text{The error is } \frac{1.288-1}{1} \times 100\% = 28.8\%$$

- 2.62** Design an accelerometer (i.e., choose m , c and k) configured as in Figure 2.23 with very small mass that will be accurate to 1% over the frequency range 0 to 50 Hz.

Solution:

Given: error < 1% , $0.2f = 50$ Hz $\rightarrow f = 250$ Hz $\rightarrow \omega = 2\pi f = 1570.8$ rad/s

$$\text{When } r=0.2, \quad 0.99 < \frac{1}{\sqrt{(1-r^2)^2 + (2\zeta r)^2}} < 1.01 \quad (\pm 1\% \text{ error})$$

$$\text{This becomes } 0.9032 + 0.1568\zeta^2 < 1 < 0.9401 + 0.1632\zeta^2$$

$$\text{Therefore, } 0.6057 < \zeta < 0.7854$$

$$\text{Choose } m = 0.01 \text{ kg, then } k = m\omega^2 = 24,674 \text{ N/m}$$

$$\text{Thus } \zeta = 0.7 = \frac{c}{2\sqrt{km}} \text{ implies that: } c = 21.99 \text{ Ns/m}$$