Calculus - Period 4

Three-Dimensional Integrals

Cylindrical Coordinates:

$$x = r\cos\theta$$
 $y = r\sin\theta$ $z = z$ (1)

$$r^2 = x^2 + y^2 \qquad \tan \theta = \frac{y}{x} \qquad z = z \qquad (2)$$

Integrating Over Cylindrical Coordinates:

 $\int_{u_1(r\cos\theta, r\sin\theta)} \int_{u_1(r\cos\theta, r\sin\theta)} f(x, y, z) dV = \int_{\alpha}^{\beta} \int_{h_1(\theta)}^{h_2(\theta)} \dots$ $\dots \int_{u_1(r\cos\theta, r\sin\theta)}^{u_2(r\cos\theta, r\sin\theta)} rf(r\cos\theta, r\sin\theta, z) dz dr d\theta$ (3)

Spherical Coordinates:

$$x = \rho \cos \theta \sin \phi \quad y = \rho \sin \theta \sin \phi \quad z = \rho \cos \phi \quad (4)$$

$$\rho^2 = x^2 + y^2 + z^2 \tag{5}$$

Integrating Over Spherical Coordinates:

If E is the spherical wedge given by $E = \{(\rho, \theta, \phi) | a \le \rho \le b, \alpha \le \theta \le \beta, c \le \phi \le d\}$, then:

$$\int \int \int_E f(x, y, z) dV = \int_a^b \int_\alpha^\beta \int_c^d \rho^2 \sin \phi \dots$$

$$\dots f(\rho \sin \phi \cos \theta, \rho \sin \phi \sin \theta, \rho \cos \phi) d\rho d\theta d\phi$$
(6)

Change of Variables:

The Jacobian of the transformation T given by x = g(u, v) and y = h(u, v) is:

$$\frac{\partial(x,y)}{\partial(u,v)} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} = \frac{\partial x}{\partial u} \frac{\partial y}{\partial v} - \frac{\partial x}{\partial v} \frac{\partial y}{\partial u} \quad (7)$$

If the Jacobian is nonzero and the transformation is one-to-one, then:

$$\iint_{R} f(x,y) dA = \iint_{S} f(x(u,v), y(u,v)) \left| \frac{\partial(x,y)}{\partial(u,v)} \right| du du dy$$
(8)

This method is similar to the one for triple integrals, for which the Jacobian has a bigger matrix and the change-of-variable equation has some more terms.

Basic Vector Field Theorems

Definitions

- A piecewise-smooth curve A union of a finite number of smooth curves.
- A closed curve A curve of which its terminal point coincides with its initial point.
- A simple curve A curve that doesn't intersect itself anywhere between its endpoints.
- An open region A region which doesn't contain any of its boundary points.
- A connected region A region D for which any two points in D can be connected by a path that lies in D.
- A simply-connected region A region *D* such that every simple closed curve in *D* encloses only points that are in *D*. It contains no holes and consists of only one piece.
- Positive orientation The positive orientation of a simple closed curve C refers to a single counterclockwise traversal of C.

Vector Field:

A vector field on \mathbb{R}^n is a function **F** that assigns to each point (x, y) in an *n*-dimensional set an *n*dimensional vector $\mathbf{F}(x, y)$. The gradient ∇f is defined by:

$$\nabla f(x, y, \ldots) = f_x \mathbf{i} + f_y \mathbf{j} + \ldots \tag{9}$$

and is called the gradient vector field. A vector field \mathbf{F} is called a conservative vector field if it is the gradient of some scalar function.

Line Integrals:

The line integral of f along C is:

$$\int_{C} f(x,y)ds = \int_{a}^{b} f(x(t),y(t))\sqrt{\left(\frac{dx}{dt}\right)^{2} + \left(\frac{dy}{dt}\right)^{2}} dt$$
(10)

The line integral of f along C with respect to x is:

$$\int_C f(x,y)dx = \int_a^b f(x(t),y(t))\frac{dx}{dt} dt \qquad (11)$$

The line integral of a vector field ${\bf F}$ along C is:

$$\int_{C} \mathbf{F} \cdot d\mathbf{r} = \int_{a}^{b} \mathbf{F}(\mathbf{r}(t)) \cdot \mathbf{r}'(t) \ dt = \int_{C} \mathbf{F} \cdot \mathbf{T} \ ds \ (12)$$

Where $\mathbf{T} = \frac{\mathbf{r}'}{|\mathbf{r}'|}$ is the unit tangent vector.

Conservative Vector Fields:

If C is the curve given by $\mathbf{r}(t)$ $(a \le t \le b)$, then:

$$\int_{C} \nabla f \cdot d\mathbf{r} = f(\mathbf{r}(b)) - f(\mathbf{r}(a))$$
(13)

The integral $\int_C \mathbf{F} \cdot d\mathbf{r}$ is independent of path in D if and only if $\int_C \mathbf{F} \cdot d\mathbf{r} = 0$ for every closed path C in D.

If $\mathbf{F}(x, y) = P(x, y)\mathbf{i} + Q(x, y)\mathbf{j}$ is a conservative vector field, then:

$$\frac{\partial P}{\partial y} = \frac{\partial Q}{\partial x} \tag{14}$$

Also, if D is an open simply-connected region, and if $\frac{\partial P}{\partial y} = \frac{\partial Q}{\partial x}$, then **F** is conservative in D.

Surfaces

Parametric Surfaces:

A surface described by $\mathbf{r}(u, v)$ is called a parametric surface. $\mathbf{r}_{\mathbf{u}} = \frac{\partial \mathbf{r}}{\partial u}$ and $\mathbf{r}_{\mathbf{v}} = \frac{\partial \mathbf{r}}{\partial v}$. For smooth surfaces ($\mathbf{r}_{\mathbf{u}} \times \mathbf{r}_{\mathbf{v}} \neq \mathbf{0}$ for every u and v) the tangent plane is the plane that contains the tangent vectors $\mathbf{r}_{\mathbf{u}}$ and $\mathbf{r}_{\mathbf{v}}$, and the vector $\mathbf{r}_{\mathbf{u}} \times \mathbf{r}_{\mathbf{v}}$ is the normal vector to the tangent plane.

Surface Areas:

For a parametric surface, the surface area is given by:

$$A = \iint_{D} |\mathbf{r}_{\mathbf{u}} \times \mathbf{r}_{\mathbf{v}}| dA \tag{15}$$

For a surface graph of g(x, y), the surface area is given by:

$$A = \iint_{D} \sqrt{1 + \left(\frac{\partial g}{\partial x}\right)^{2} + \left(\frac{\partial g}{\partial y}\right)^{2}} dA \qquad (16)$$

Surface Integrals:

For a parametric surface, the surface integral is given by:

$$\iint_{S} f(x, y, z) \, dS = \iint_{D} f(\mathbf{r}(u, v)) |\mathbf{r}_{\mathbf{u}} \times \mathbf{r}_{\mathbf{v}}| dA$$
(17)

For a surface graph of g(x, y), the surface integral is given by:

$$\iint_{S} f(x, y, z) \, dS =$$
$$\iint_{D} f(x, y, g(x, y)) \sqrt{1 + \left(\frac{\partial g}{\partial x}\right)^{2} + \left(\frac{\partial g}{\partial y}\right)^{2}} \, dA$$
(18)

Normal Vectors:

For a parametric surface, the normal vector is given by: $\mathbf{n} = \mathbf{v} \cdot \mathbf{n}$

$$\mathbf{n} = \frac{\mathbf{r}_{\mathbf{u}} \times \mathbf{r}_{\mathbf{v}}}{|\mathbf{r}_{\mathbf{u}} \times \mathbf{r}_{\mathbf{v}}|} \tag{19}$$

For a surface graph of g(x, y), the normal vector is given by:

$$\mathbf{n} = \frac{-\frac{\partial g}{\partial x}\mathbf{i} - \frac{\partial g}{\partial y}\mathbf{j} + \mathbf{k}}{\sqrt{1 + \left(\frac{\partial g}{\partial x}\right)^2 + \left(\frac{\partial g}{\partial y}\right)^2}}$$
(20)

Flux:

If \mathbf{F} is a vector field on a surface S with unit normal vector \mathbf{n} , then the surface integral of \mathbf{F} over S is:

$$\iint_{S} \mathbf{F} \cdot d\mathbf{S} = \iint_{S} \mathbf{F} \cdot \mathbf{n} \, dS \tag{21}$$

This integral is also called the flux of \mathbf{F} across S. For a parametric surface, the flux is given by:

$$\iint_{S} \mathbf{F} \cdot d\mathbf{S} = \iint_{D} \mathbf{F} \cdot (\mathbf{r}_{\mathbf{u}} \times \mathbf{r}_{\mathbf{v}}) \, dA \qquad (22)$$

For a surface graph of g(x, y), the flux is given by:

$$\iint_{S} \mathbf{F} \cdot d\mathbf{S} = \iint_{D} \left(-P \frac{\partial g}{\partial x} - Q \frac{\partial g}{\partial y} + R \right) \, dA \quad (23)$$

Advanced Vector Field Theorems

Curl:

If $\mathbf{F} = P\mathbf{i} + Q\mathbf{j} + R\mathbf{k}$, then the curl of \mathbf{F} , denoted by curl \mathbf{F} or also $\nabla \times \mathbf{F}$, is defined by:

$$\left(\frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z}\right)\mathbf{i} + \left(\frac{\partial P}{\partial z} - \frac{\partial R}{\partial x}\right)\mathbf{j} + \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y}\right)\mathbf{k}$$
(24)

If f is a function of three variables, then:

$$\operatorname{curl}(\nabla f) = \mathbf{0} \tag{25}$$

This implies that if **F** is conservative, then curl $\mathbf{F} = \mathbf{0}$. The converse is only true if **F** is defined on all of \mathbb{R}^n . So if **F** is defined on all of \mathbb{R}^n and if curl $\mathbf{F} = \mathbf{0}$, then **F** is a conservative vector field.

Divergence:

If $\mathbf{F} = P\mathbf{i} + Q\mathbf{j} + R\mathbf{k}$, then the divergence of \mathbf{F} , denoted by div \mathbf{F} or also $\nabla \cdot \mathbf{F}$, is defined by:

div
$$\mathbf{F} = \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z}$$
 (26)

If \mathbf{F} is a vector field on \mathbb{R}^n , then div curl $\mathbf{F} = 0$. If div $\mathbf{F} = 0$, then \mathbf{F} is said to be incompressible. Note that curl \mathbf{F} returns a vector field and div \mathbf{F} returns a scalar field.

Green's Theorem:

Let C be a positively oriented piecewise-smooth simple closed curve in the plane and D be the region bounded by C. Now:

$$\int_{C} P \, dx + Q \, dy = \iint_{D} \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA \quad (27)$$

This can also be useful for calculating areas. To calculate an area, take functions P and Q such that $\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} = 1$ and then apply Green's theorem. In vector form, Green's theorem can also be written as:

$$\int_{C} \mathbf{F} \cdot d\mathbf{r} = \iint_{D} (\operatorname{curl} \mathbf{F}) \cdot \mathbf{k} \, dA \qquad (28)$$

$$\int_{C} \mathbf{F} \cdot \mathbf{n} \, ds = \iint_{D} \operatorname{div} \, \mathbf{F}(x, y) \, dA \qquad (29)$$

Stoke's Theorem:

Let S be an oriented piecewise-smooth surface that is bounded by a simple, closed, piecewise-smooth boundary curve C with positive orientation. Let \mathbf{F} be a vector field that contains S. Then:

$$\int_{C} \mathbf{F} \cdot d\mathbf{r} = \iint_{S} \operatorname{curl} \mathbf{F} \cdot d\mathbf{S}$$
(30)

The Divergence Theorem:

Let E be a simple solid region and let S be the boundary surface of E, given with positive (outward) orientation. Let \mathbf{F} be a vector field on an open region that contains E. Then:

$$\iint_{S} \mathbf{F} \cdot d\mathbf{S} = \iiint_{E} \operatorname{div} \mathbf{F} \, dV \tag{31}$$